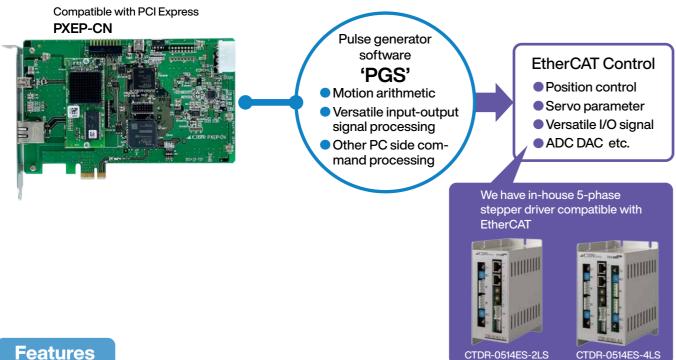
The Multifunction Motion Controller

EtherCAT

The Controller that fused hardware's high speed and software's flexibility



Enhancing of motion function and software processing speed

The existing product needed waiting time between PC and controller, because of the processing related to control is controlled on PC dependently. However, this product process high speed in "PGS", even when complex control and function. You can share software with RTEX products except for difference in hardware function and communication standards.

All-in-one board

The biggest feature of PXEP-CN is being All-in-one board that included "EtherCAT communication + Realtime control + Motion control" in only one board. Therefore, it is possible to develop with Visual Studio.

Pitch error correction

It is the function that correct pitch errors by positioning that adding correction amount to command position when driving controlled axis, in advance have measured regular interval pitch error of a transmission mechanism (e.g., screw).

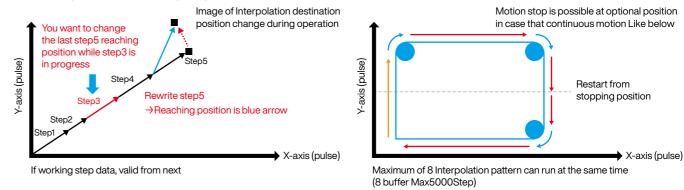
Compatible with wide variety devices

We provide functions to be able to control CIA401/CIA402 compatible slaves easily. We have verification results for over 50 types of slaves from over 25 companies and connection manual of compatible devices. The product that has passed official testing by EtherCAT Test Center (ETC) certified by ETG can be supported if the environment is set up if also a product not in the manual.

Main functions

Interpolation control: circular and ellipse interpolation, Helical interpolation, and third dimension interpolation function

Up to 5000 steps of interpolated data can be recorded in "PGS", change interpolation data in working, revise and interpolate reached position, and pause interpolation motion are possible. Also restart from paused position and exchange interpolation axis (XY-axis \rightarrow XZ-axis) are possible.



High-accuracy synchronous · (axis)interlocking function · Gantry control · Soft landing function

Overshoot at a stop such as bonding machine may cause clash and damage to parts, but the soft-landing function

suppresses overshoot when stopping, protecting machines, materials, and workpieces. It is possible to set

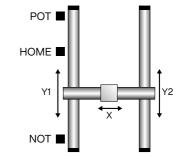
speed down when the

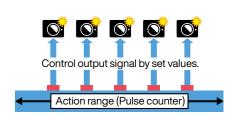
moment that puts on or

press material to pallet.

We provided gantry control as basic function. This function applies axis interlocking functions, and by setting Y2-axis as interlocked axis of Y1-axis, Y2-axis automatically track by needing only to send operation to unit Y1-axis.

You can set output signal that can use for flipping ON/OFF of strobe and sensor to Motor position information.





Others

- 31-Axis Motion Control and I/O control are possible (Motion control is a maximum of 31-axis)
- Speed, acceleration, deceleration can set in 1 pps between 1 pps~400 Mpps.
- By the Worktable (X, Y, Z) interlock to encoder information of conveyor, complex action is possible without stopping motion axis
- Use versatile input as trigger signal, and it can use for motion start and synchronous control set in advance.
- The cam axis control function can choose from 6 types of cam ark, Constant Acceleration / Harmonic / Cycloid / Modified Trapezoid / Modified Sine / Modified Constant Speed.



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